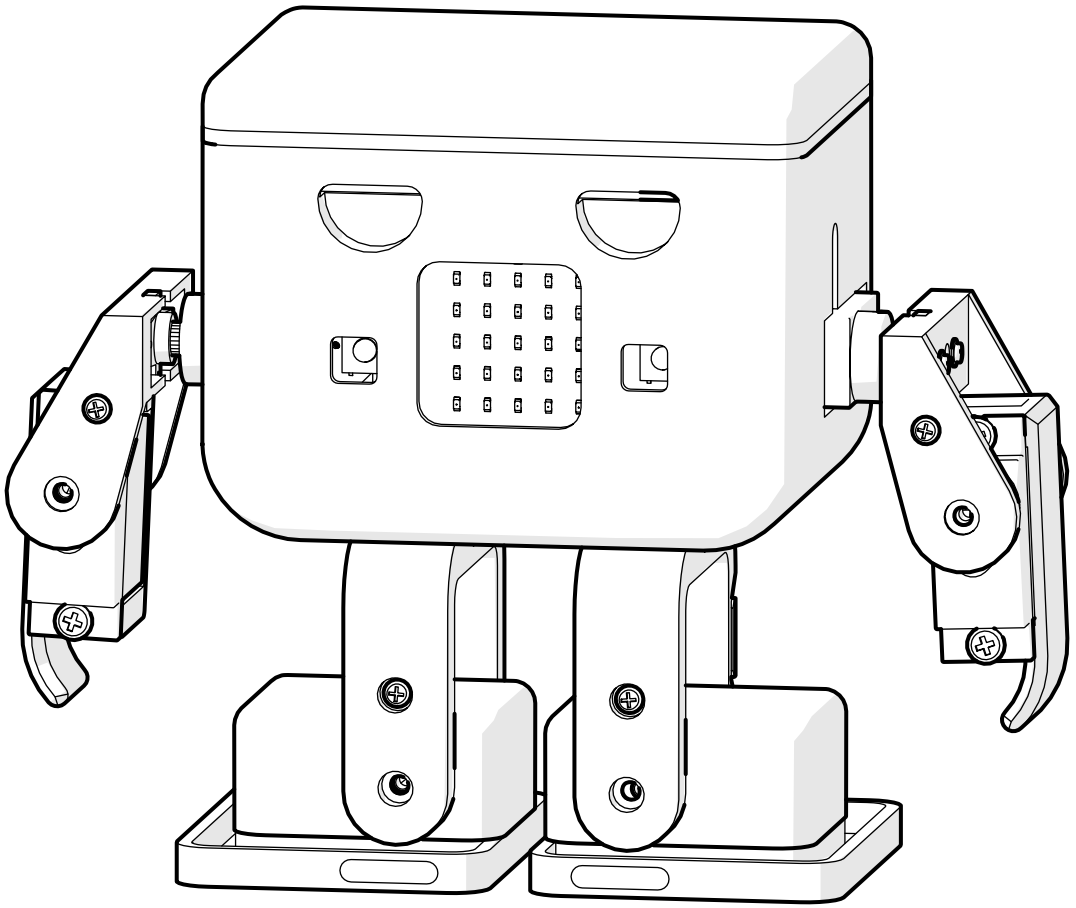
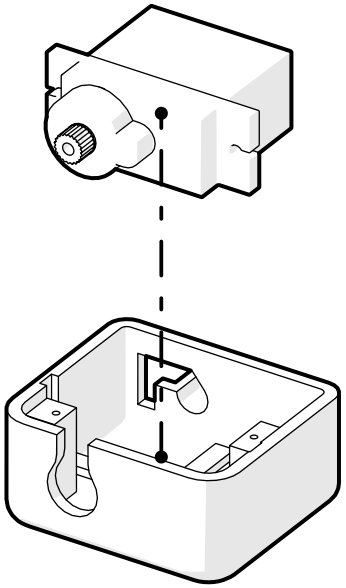
Microbit版OTTO机器人

组装说明书

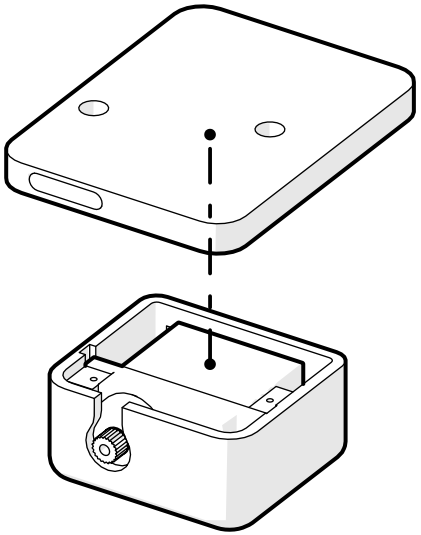


由于版本迭代更新，请以实物为准，
电路板接线与程序调试，请访问论坛kittenbot.cn/bbs的OTTO机器人专区
更多技术支持请加入爱上小喵科技Q群:568084773

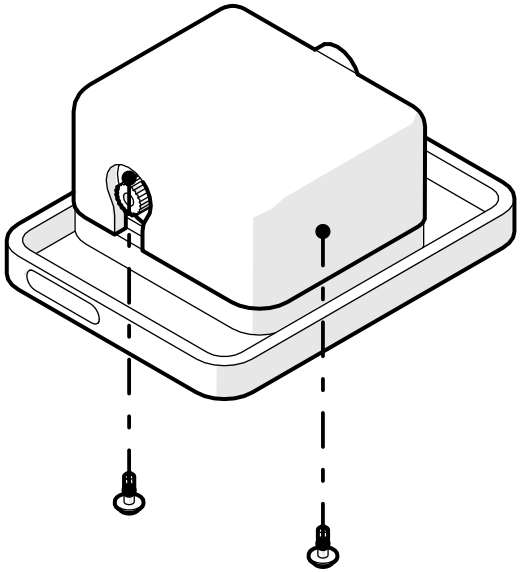
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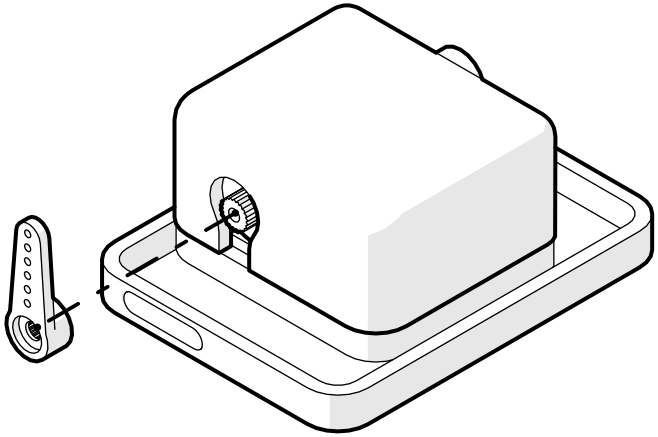
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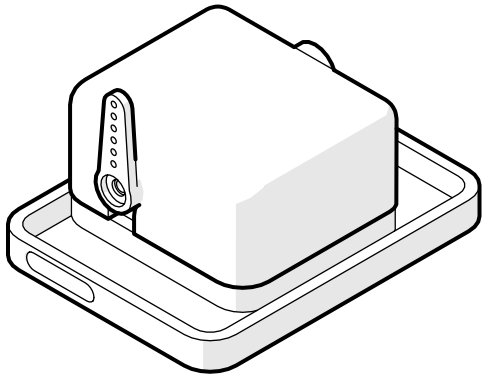
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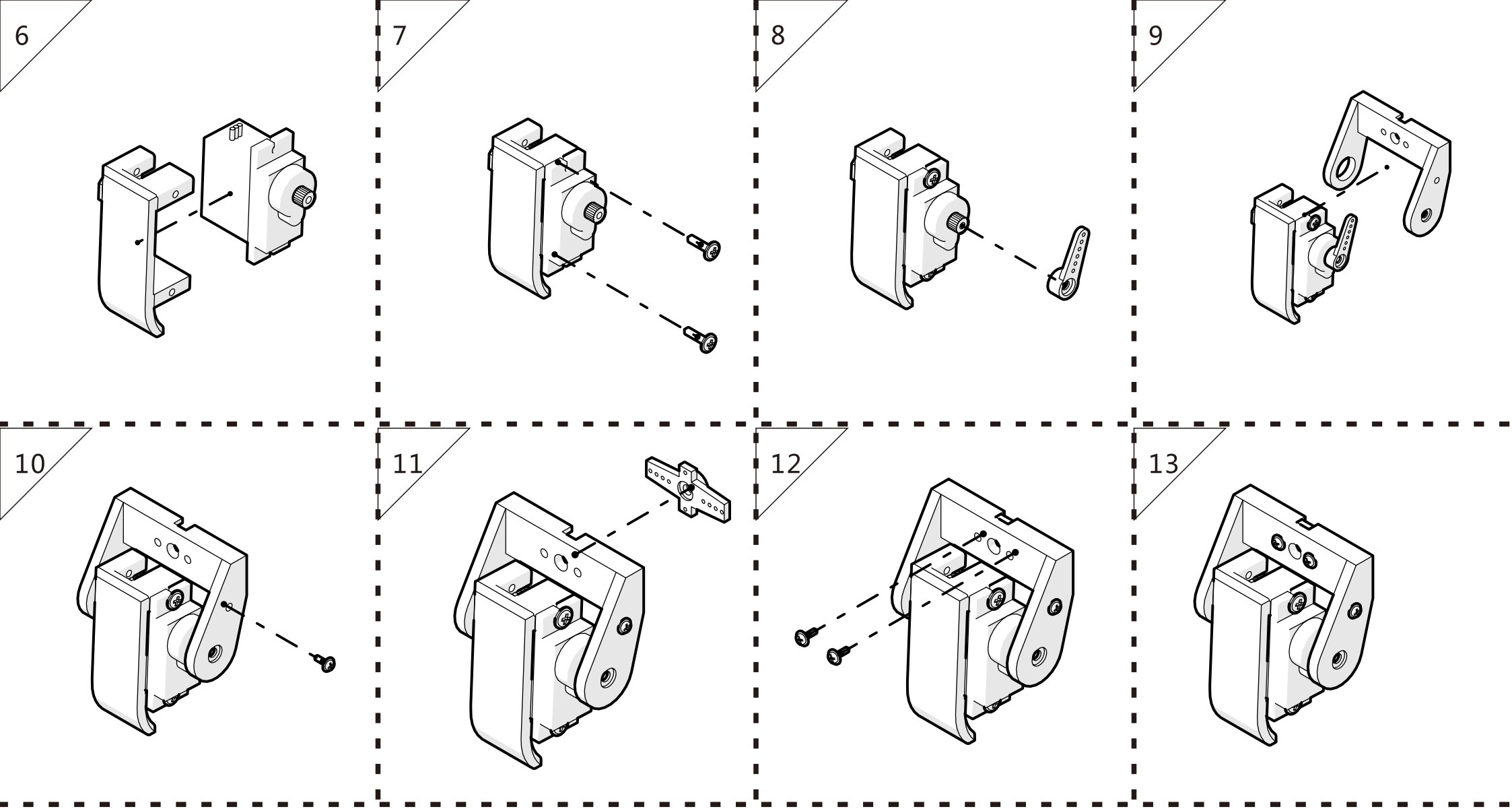


请保证舵机此时的角度是旋转到90度。

让舵机角度停留在90度有两种方法：

1、舵机的范围是0-180，带上舵盘旋动，找出两个极限位置（0度和180度，然后取中间，即为90度）

2、或者写程序控制舵机角度停留在90度



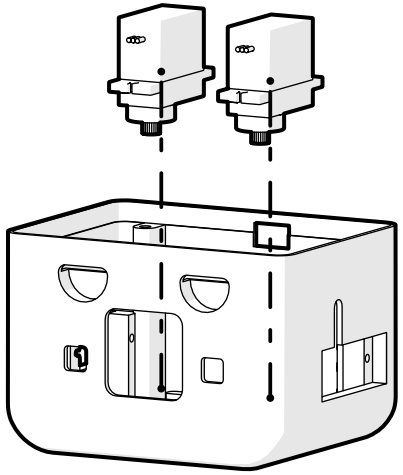
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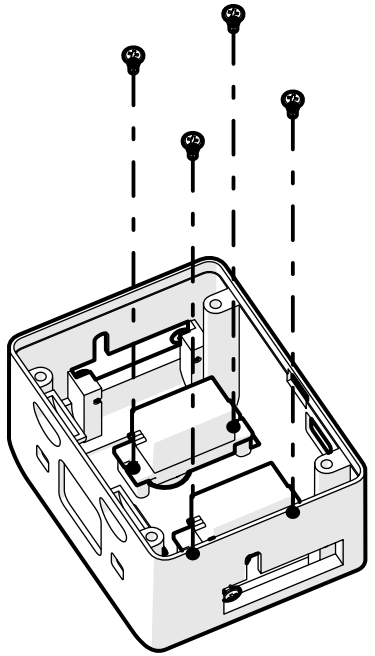
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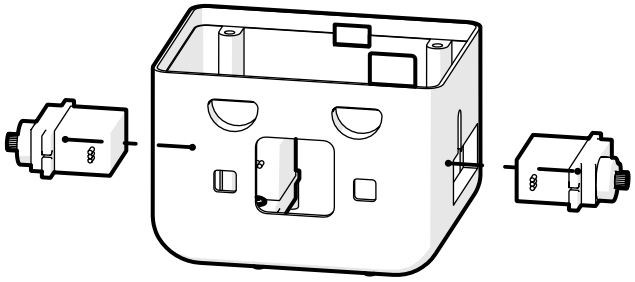
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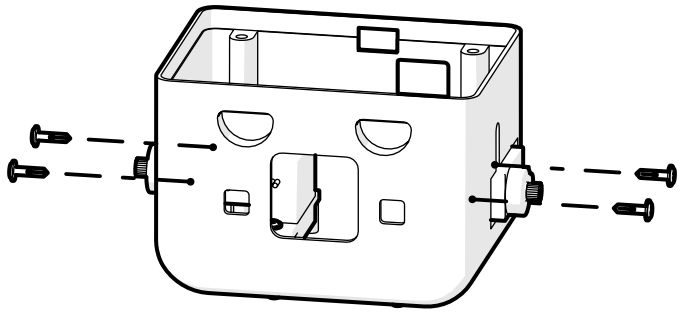
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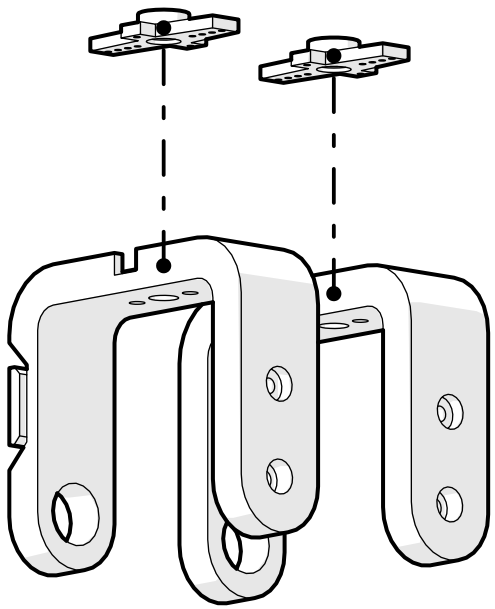
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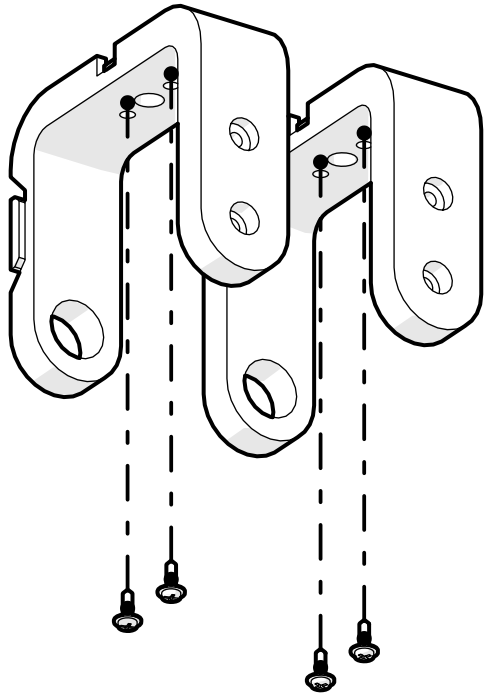
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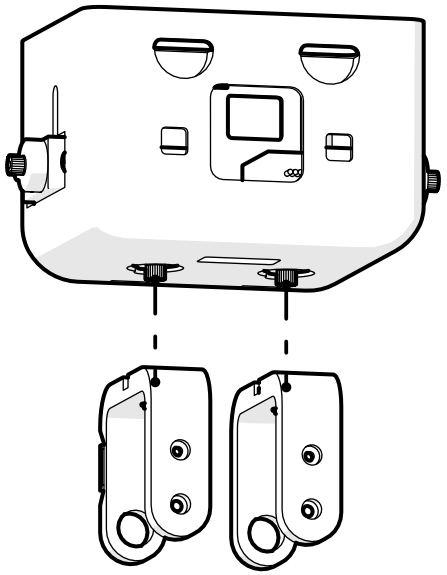
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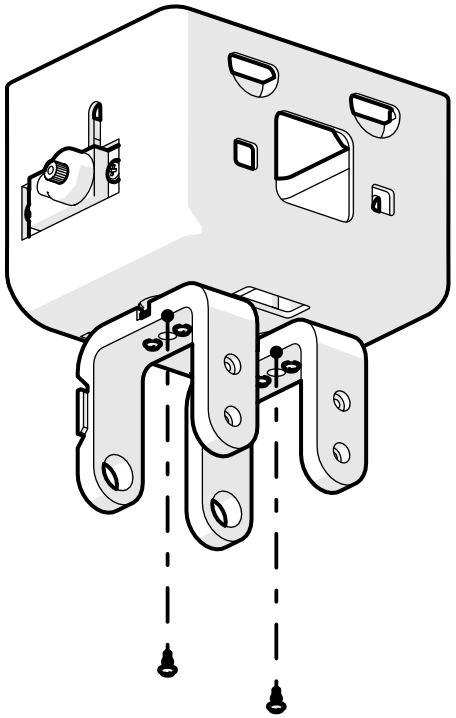
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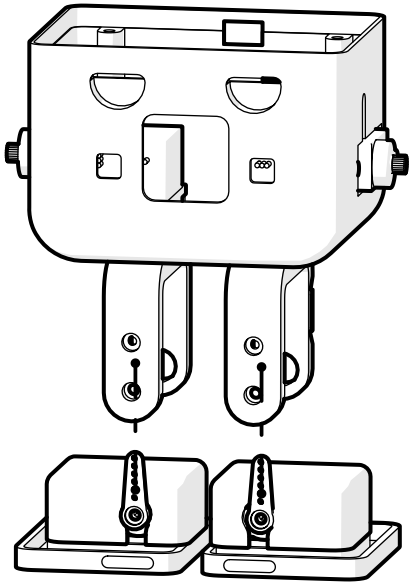
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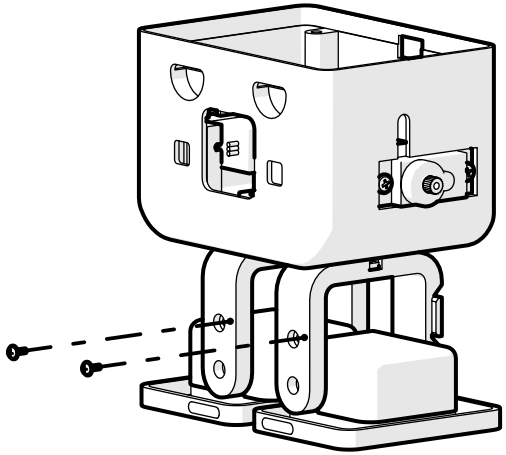
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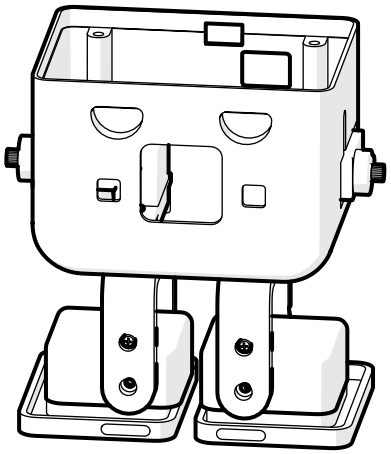
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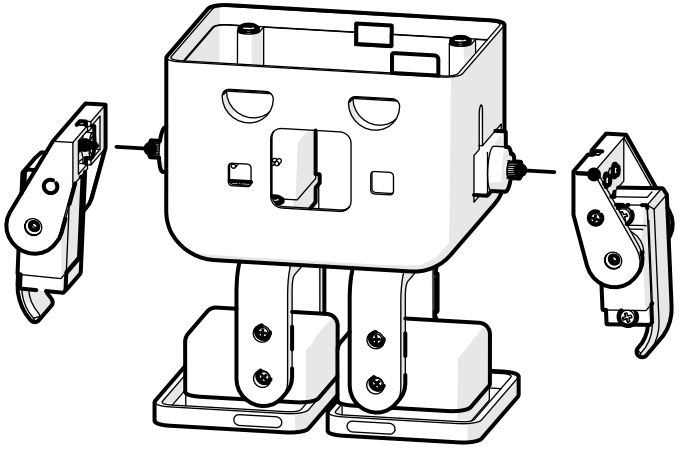
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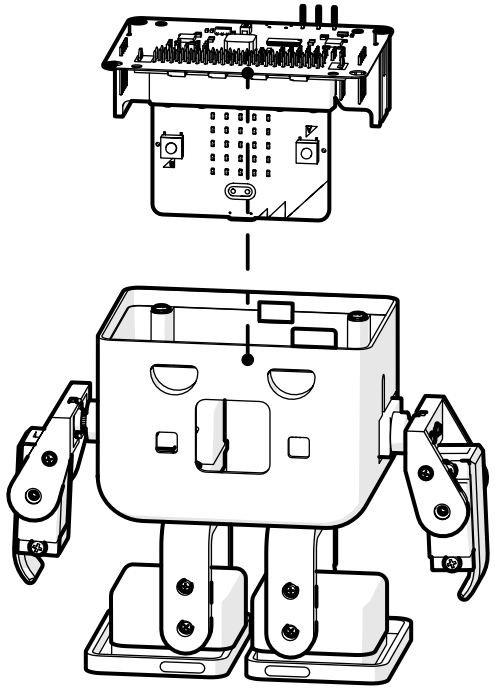
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