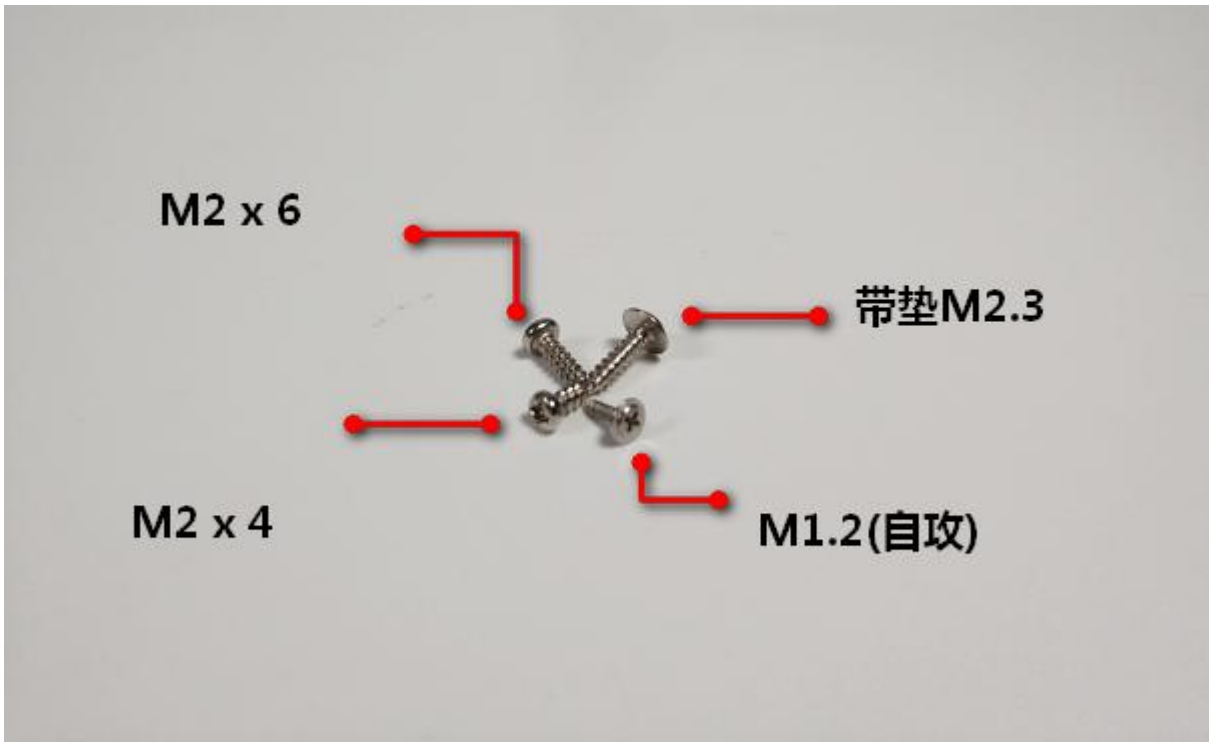
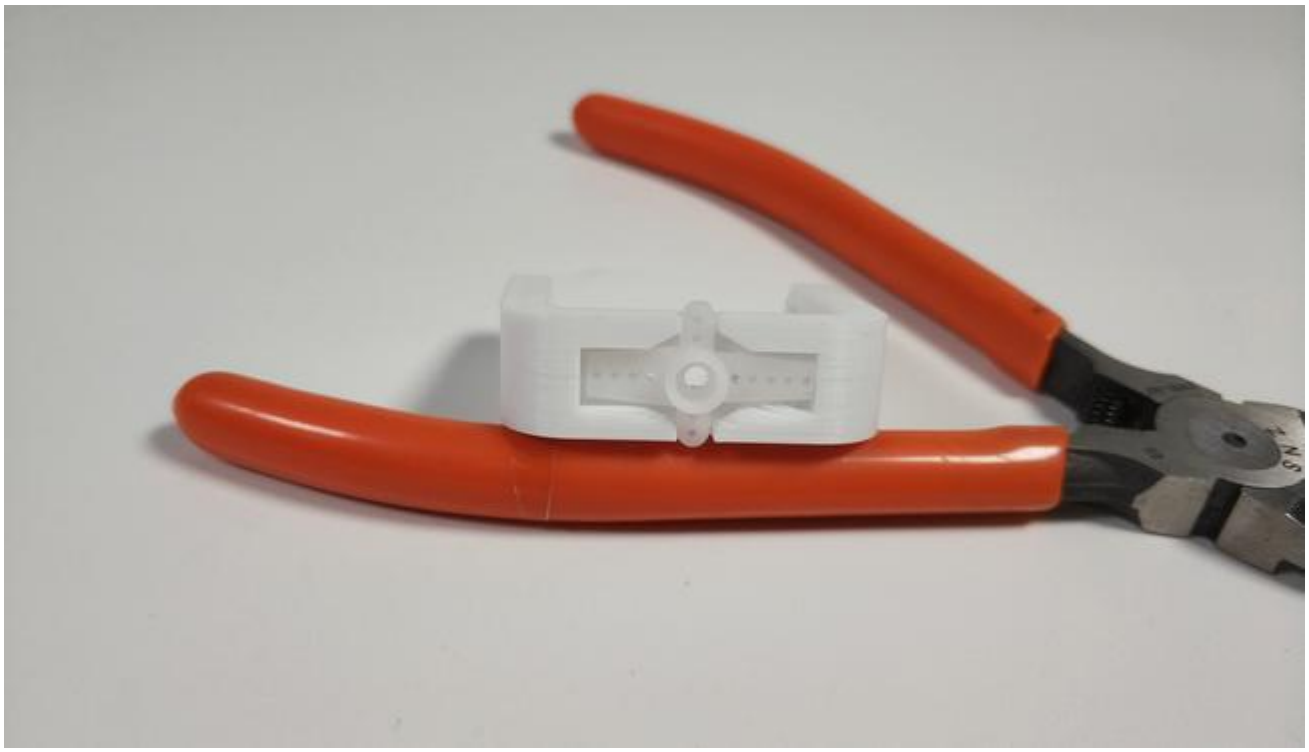
Instruction Manual

1.Screws:



2.Shearing the servo mount as the following pics:

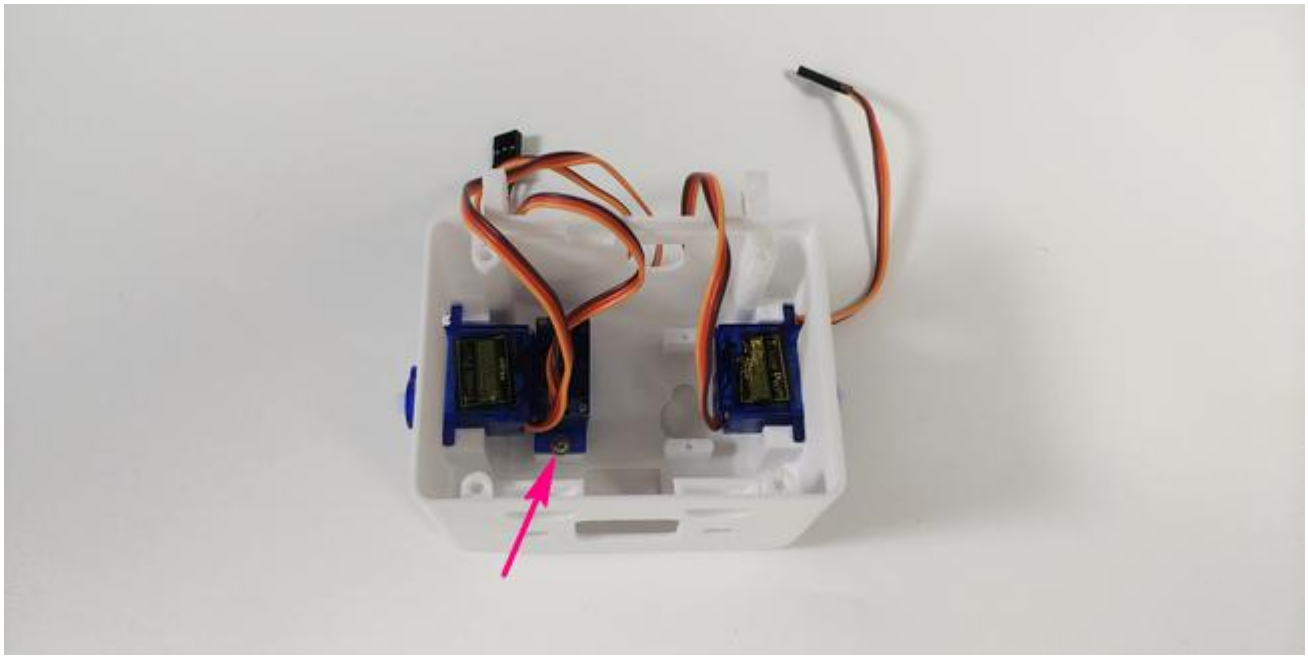


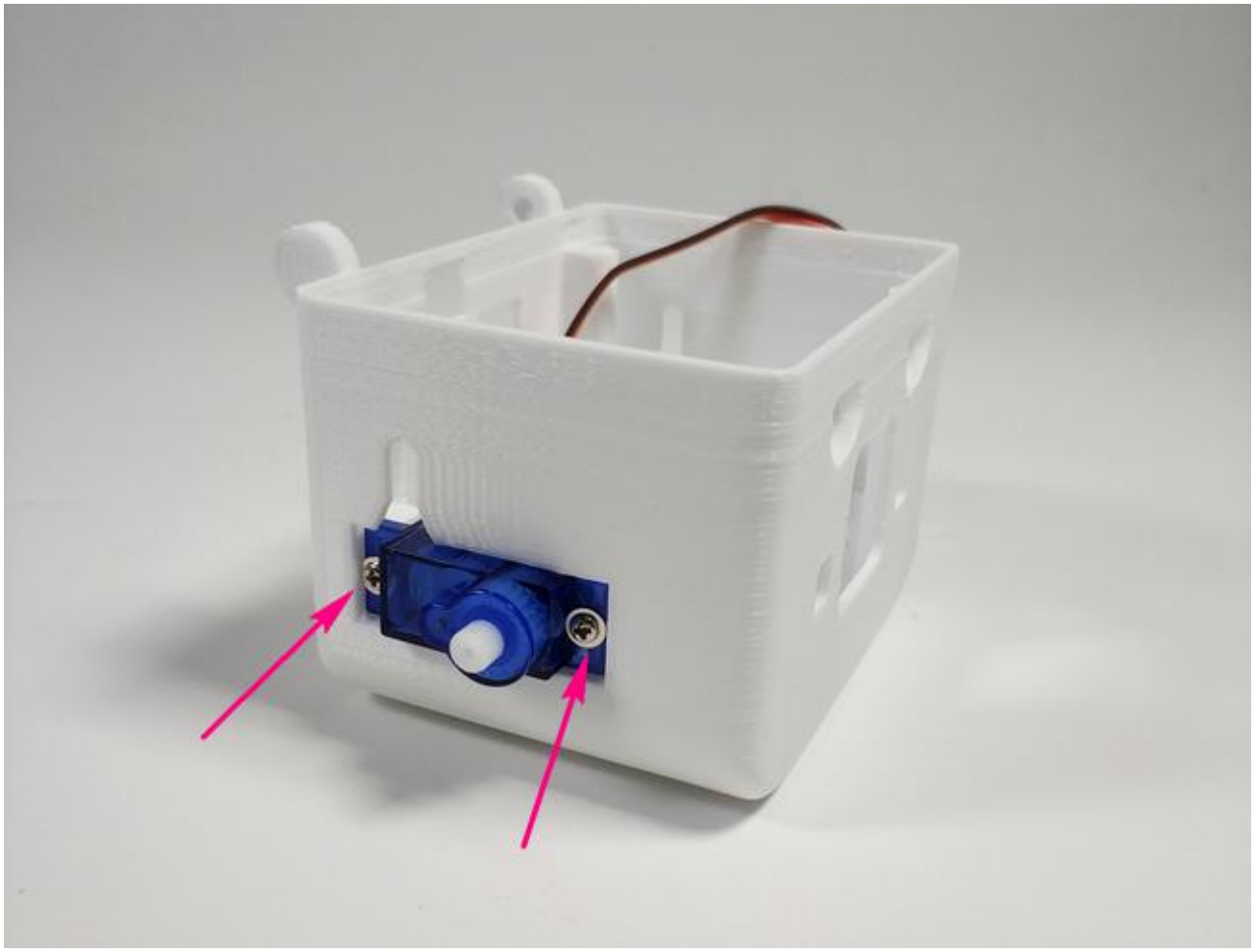


3. Screw on 2pcs M1.2 screws:

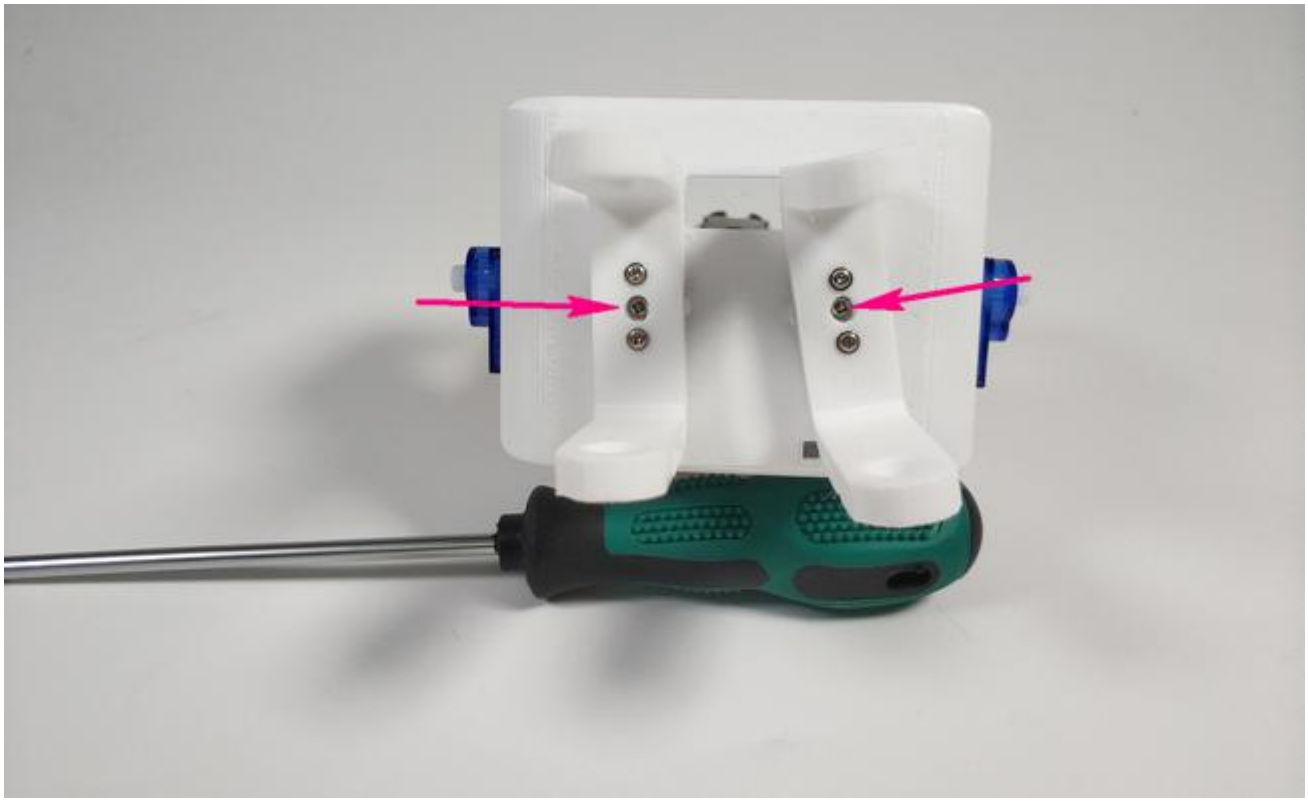


4. Put the servos into the mount by using the 2pcs of M2.3 screws:

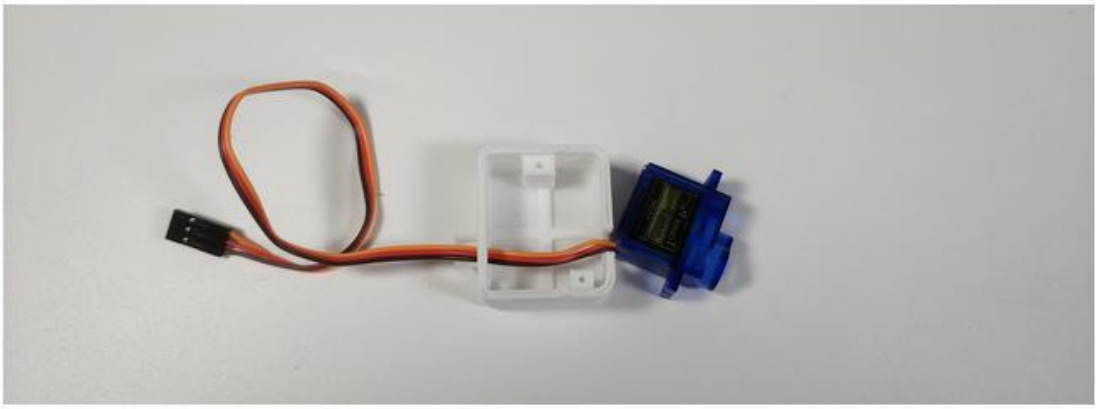


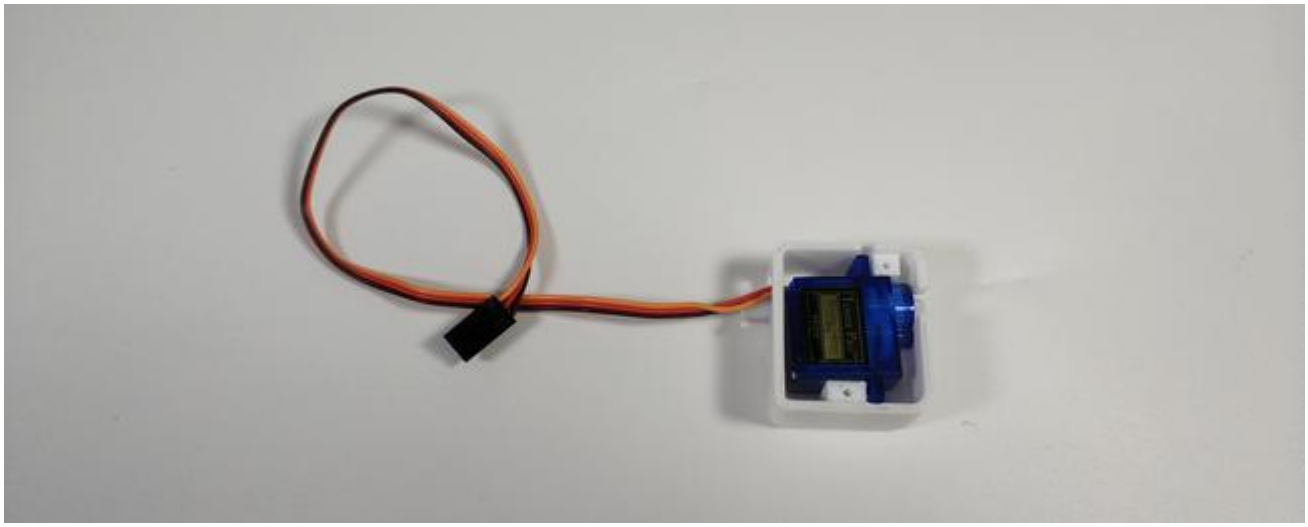


5. Using 1pc M2x4 Screw the tighten the servo and the support

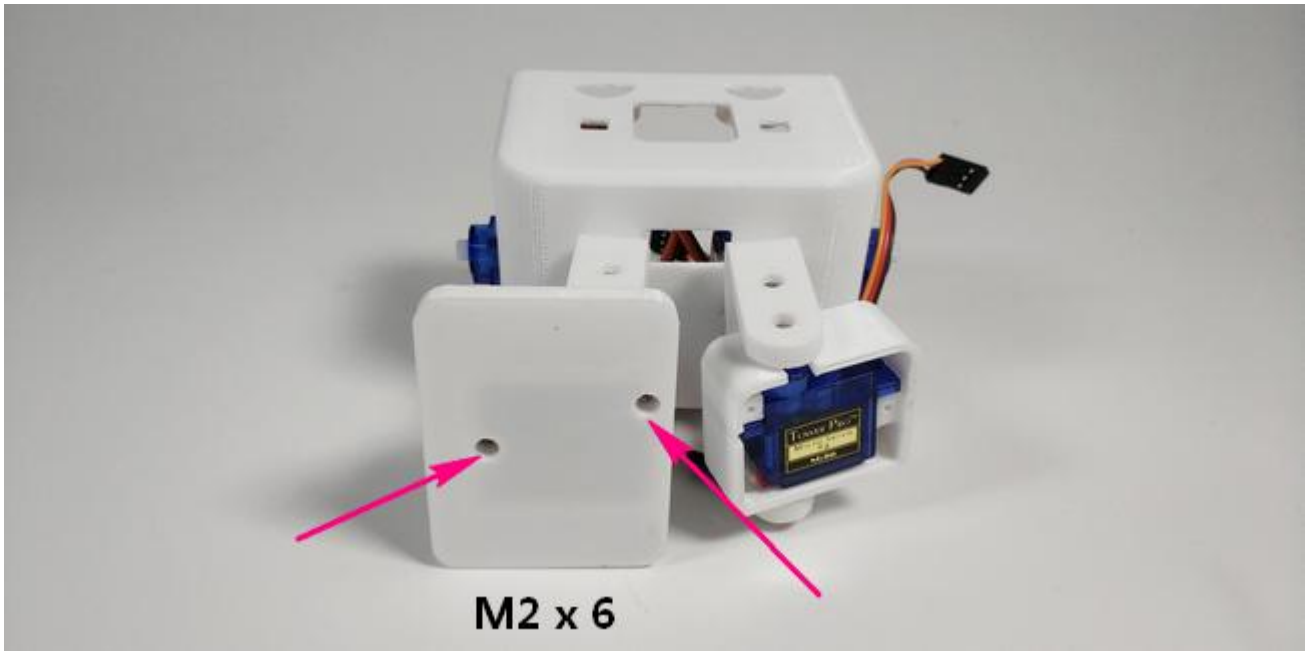


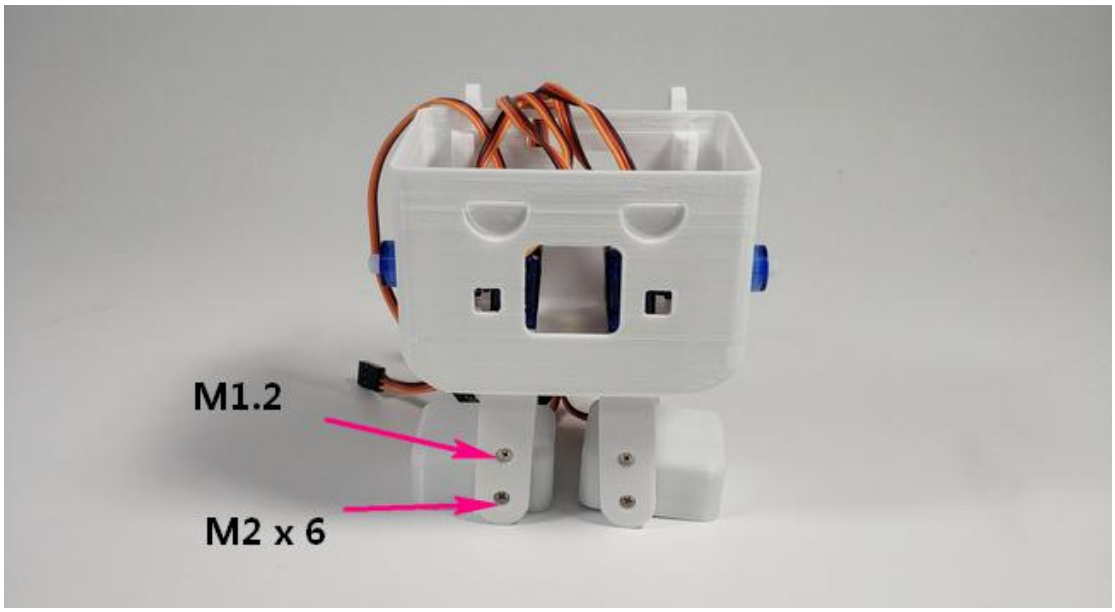
6. Install the foot servo as follow:



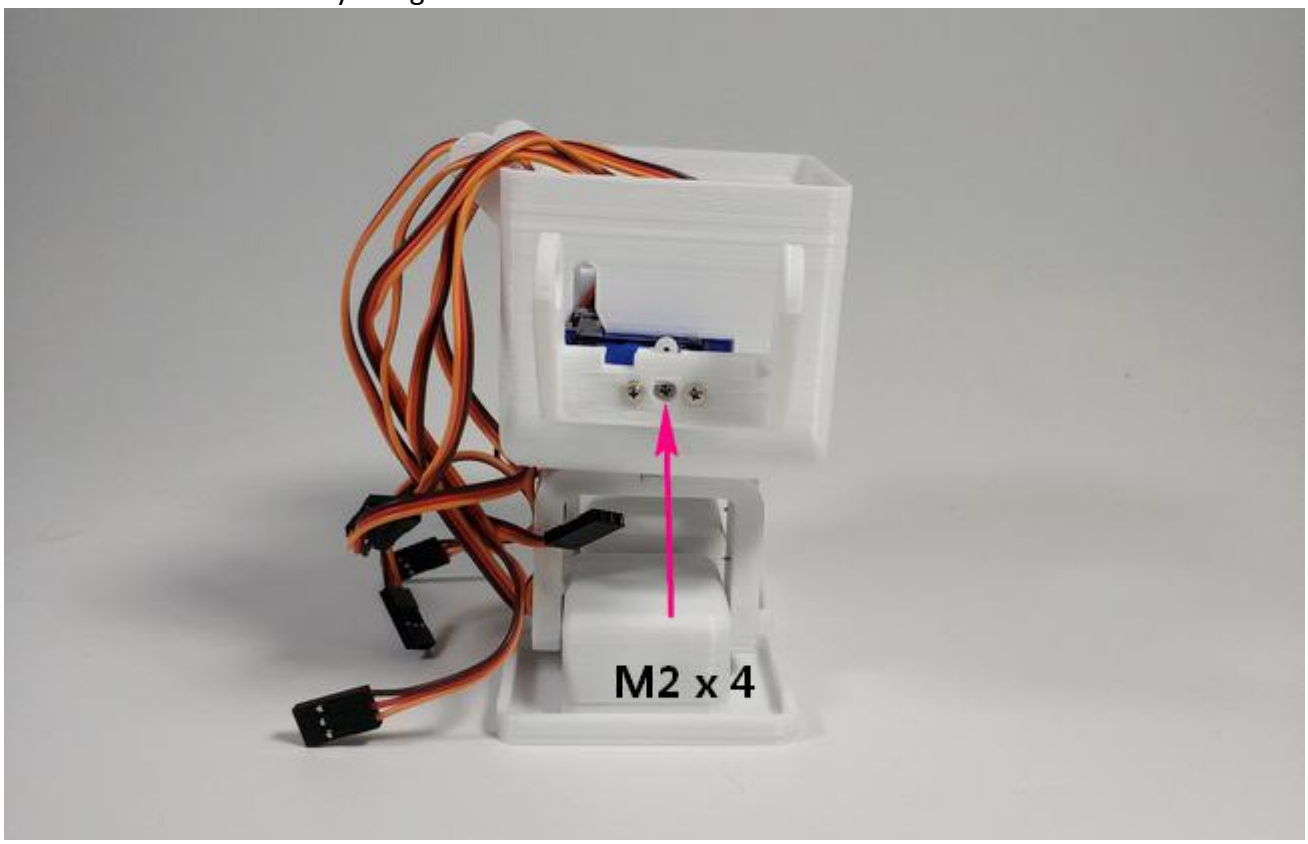


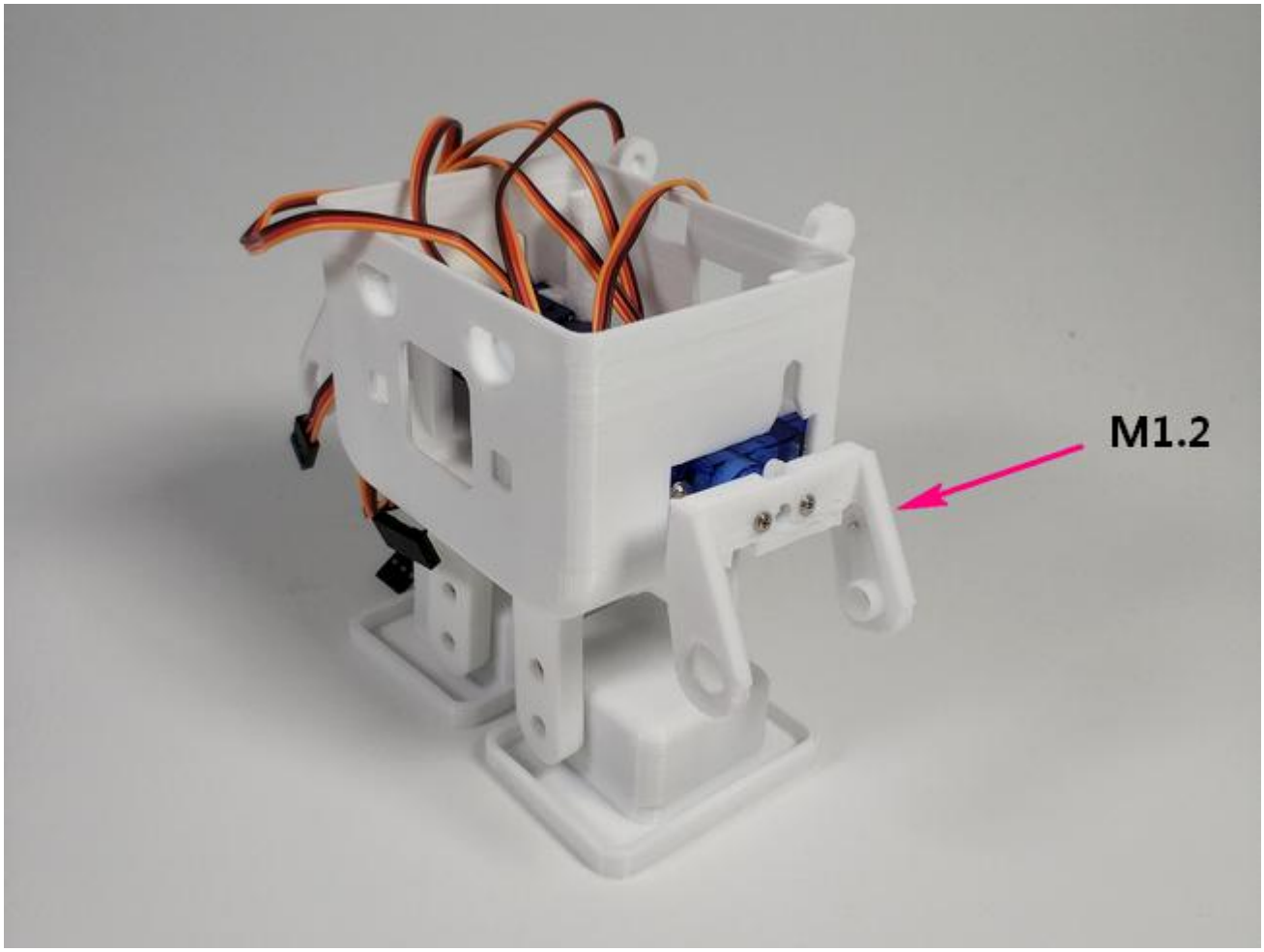
7. and tighten the screws:



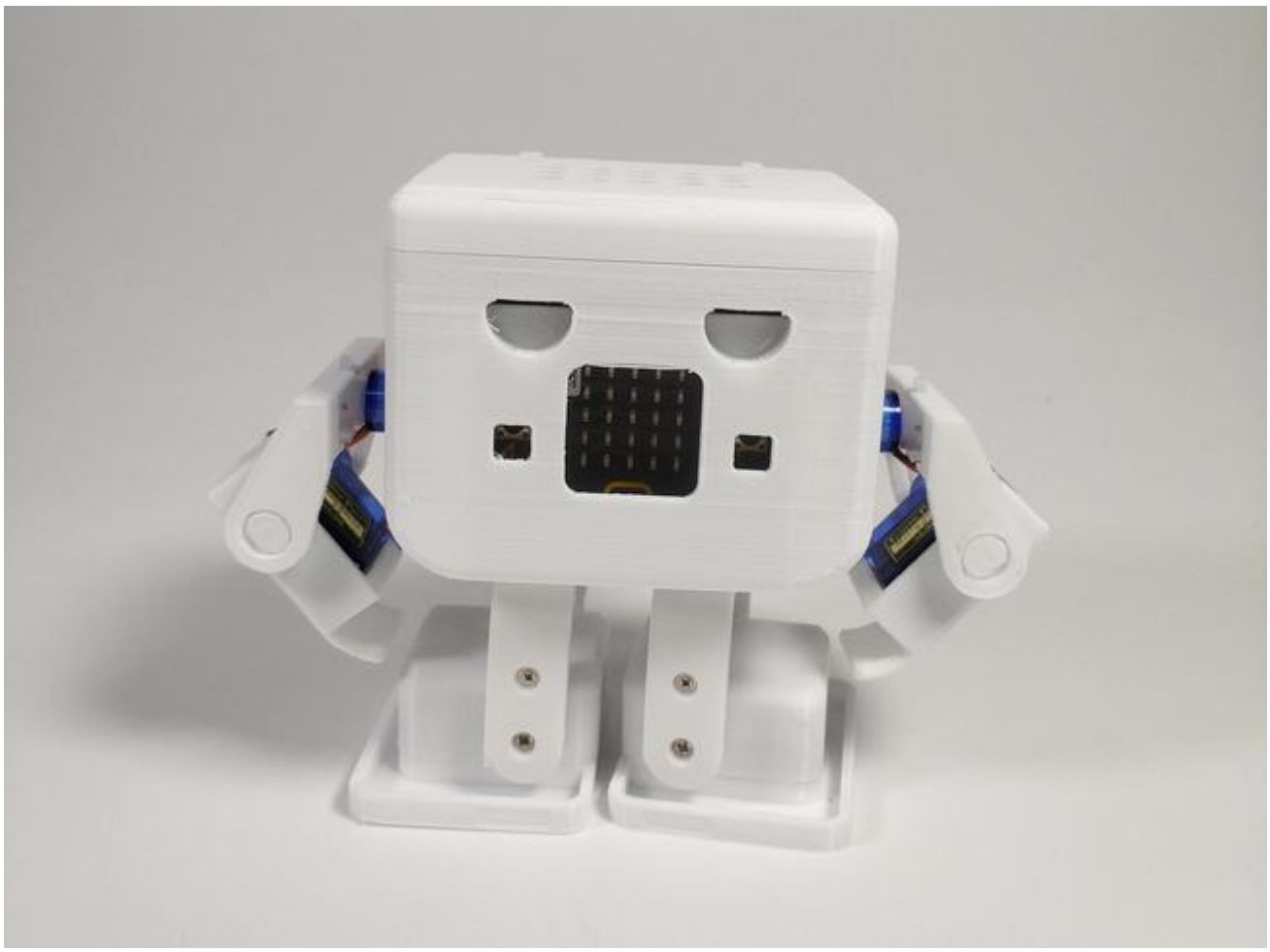


8. Install the robot arm by using the M1.2 screws as follow:

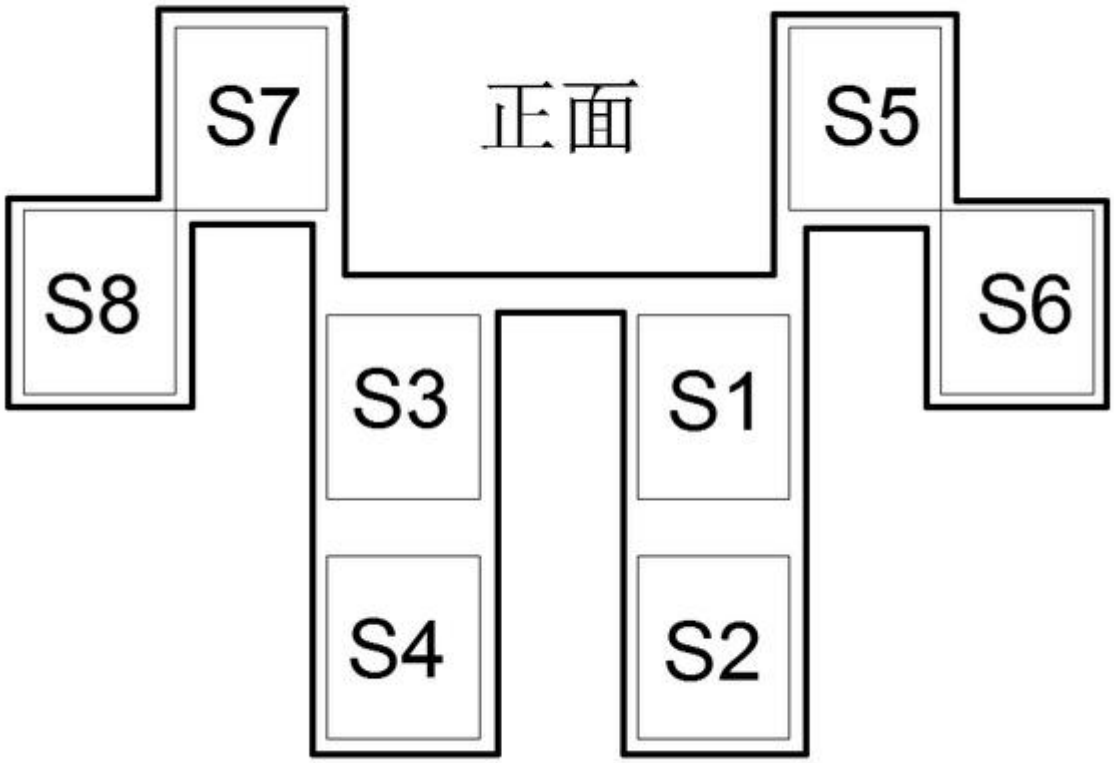




9. the installation procedure of the arm is similar to the foot:



10.at last,connect the wires as follow:


S7
正面
S5
S8
S6
S3
S1
S4
S2